



**PRO** - SATA Product Manual

ST10000DM0004

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July 2016

## Document Revision History

| Revision | Date       | Pages affected and Description of changes                          |
|----------|------------|--|
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| Rev. B)  | 07/18/2016 | 7 & 16: Non-rcvr rd errs = $10^{15}$ ; POH = 8760; RWL = <300TB/yr |

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|   |          |
|---|----------|
| <b>Seagate® Technology Support Services</b> ..... | <b>4</b> |
|---|----------|

---

|  |          |
|--|----------|
| <b>1.0 Introduction</b> .....            | <b>5</b> |
| 1.1 About the Serial ATA interface ..... | 5        |

---

|  |          |
|--|----------|
| <b>2.0 Drive specifications</b> .....  | <b>6</b> |
| 2.1 Specification summary tables .....   | 6        |
| 2.2 Formatted capacity .....   | 8        |
| 2.2.1 LBA mode .....   | 8        |
| 2.3 Recording and interface technology .....                                     | 8        |
| 2.4 Start/stop times .....   | 8        |
| 2.5 Power specifications .....   | 9        |
| 2.5.1 Power consumption .....  | 9        |
| 2.5.2 Conducted noise .....  | 10       |
| 2.5.3 Voltage tolerance .....  | 10       |
| 2.5.4 Extended Power Conditions - PowerChoice™ .....                             | 11       |
| 2.6 Environmental limits .....   | 13       |
| 2.6.1 Temperature .....  | 13       |
| 2.6.2 Humidity .....   | 13       |
| 2.6.3 Effective Altitude (sea level) .....                                       | 13       |
| 2.6.4 Shock .....  | 14       |
| 2.6.5 Vibration .....  | 14       |
| 2.7 Acoustics .....  | 15       |
| 2.8 Test for Prominent Discrete Tones (PDTs) .....                               | 15       |
| 2.9 Electromagnetic immunity .....   | 15       |
| 2.10 Reliability .....   | 16       |
| 2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF) ..... | 16       |
| 2.10.2 Storage .....   | 16       |
| 2.10.3 Warranty .....  | 16       |
| 2.11 Agency certification .....  | 17       |
| 2.11.1 Safety certification .....  | 17       |
| 2.11.2 Electromagnetic compatibility .....                                       | 17       |
| 2.11.3 FCC verification .....  | 17       |
| 2.12 Environmental protection .....  | 18       |
| 2.12.1 European Union Restriction of Hazardous Substances (RoHS) Directive ..... | 18       |
| 2.12.2 China Requirements — China RoHS 2 .....                                   | 18       |
| 2.13 Corrosive environment .....   | 19       |
| 2.14 Shipping, Repair and Returns .....  | 19       |

---

|            |   |           |
|------------|---|-----------|
| <b>3.0</b> | <b>Configuring and mounting the drive</b> ..... | <b>20</b> |
| 3.1        | Handling and static-discharge precautions ..... | 20        |
| 3.2        | Configuring the drive .....                     | 20        |
| 3.3        | Serial ATA cables and connectors .....          | 20        |
| 3.4        | Drive mounting .....                            | 21        |
| 3.4.1      | Mechanical specifications .....                 | 21        |

---

|            |  |           |
|------------|--|-----------|
| <b>4.0</b> | <b>Serial ATA (SATA) interface</b> .....               | <b>22</b> |
| 4.1        | Hot-Plug compatibility .....                           | 22        |
| 4.2        | Serial ATA device plug connector pin definitions ..... | 22        |
| 4.3        | Supported ATA commands .....                           | 23        |
| 4.3.1      | Identify Device command .....                          | 25        |
| 4.3.2      | Set Features command .....                             | 28        |
| 4.3.3      | S.M.A.R.T. commands .....                              | 29        |

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# 1.0 Introduction

This manual describes the functional, mechanical and interface specifications for the following:  
Seagate® BarraCuda® Pro Serial ATA model drives:

| Standard 512E models |
|----------------------|
| ST10000DM0004        |

These drives provide the following key features:

- 256 MB data buffer.
- 7200 RPM spindle speed.
- Full-track multiple-sector transfer capability without local processor intervention.
- High instantaneous (burst) data-transfer rates (up to 600MB per second).
- Native Command Queuing with command ordering to increase performance in demanding applications.
- Perpendicular recording technology provides the drives with increased areal density.
- PowerChoice™ for selectable power savings
- SeaTools™ diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- State-of-the-art cache and on-the-fly error-correction algorithms.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Supports latching SATA cables and connectors.
- Top Cover Attached motor for excellent vibration tolerance
- Worldwide Name (WWN) capability uniquely identifies the drive.

|             |   |
|-------------|---|
| <b>Note</b> | Seagate recommends validating the configuration with the selected HBA/RAID controller manufacturer to ensure use of full capacity is supported. |
|-------------|---|

## 1.1 About the Serial ATA interface

The Serial ATA interface provides several advantages over the traditional (parallel) ATA interface. The primary advantages include:

- Easy installation and configuration with true plug-and-play connectivity.  
It is not necessary to set any jumpers or other configuration options.
- Thinner and more flexible cabling for improved enclosure airflow and ease of installation.
- Scalability to higher performance levels.

In addition, Serial ATA makes the transition from parallel ATA easy by providing legacy software support. Serial ATA was designed to allow users to install a Serial ATA host adapter and Serial ATA disk drive in the current system and expect all of the existing applications to work as normal.

The Serial ATA interface connects each disk drive in a point-to-point configuration with the Serial ATA host adapter. There is no master/slave relationship with Serial ATA devices like there is with parallel ATA. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both “masters” on two separate ports. This essentially means both drives behave as if they are Device 0 (master) devices.

|             |   |
|-------------|---|
| <b>Note</b> | The host adapter may, optionally, emulate a master/slave environment to host software where two devices on separate Serial ATA ports are represented to host software as a Device 0 (master) and Device 1 (slave) accessed at the same set of host bus addresses. A host adapter that emulates a master/slave environment manages two sets of shadow registers. This is not a typical Serial ATA environment. |
|-------------|---|

The Serial ATA host adapter and drive share the function of emulating parallel ATA device behavior to provide backward compatibility with existing host systems and software. The Command and Control Block registers, PIO and DMA data transfers, resets, and interrupts are all emulated.

The Serial ATA host adapter contains a set of registers that shadow the contents of the traditional device registers, referred to as the Shadow Register Block. All Serial ATA devices behave like Device 0 devices. For additional information about how Serial ATA emulates parallel ATA, refer to the “Serial ATA: High Speed Serialized AT Attachment” specification. The specification can be downloaded from [www.serialata.org](http://www.serialata.org).

## 2.0 Drive specifications

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate the following drive models:

| Standard 512E models |
|----------------------|
| ST10000DM0004        |

### 2.1 Specification summary tables

The specifications listed in the following tables are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

**Table 1 Drive specifications summary**

| Drive specification*                                   | ST10000DM0004   |
|--|---|
| Formatted (512 bytes/sector)**                         | 10TB  |
| Guaranteed sectors                                     | (see <a href="#">Section 2.2</a> )                              |
| Heads  | 14  |
| Discs  | 7   |
| Bytes per logical sector                               | 512   |
| Bytes per physical sector                              | 4096  |
| Recording density, KBPI (Kb/in max)                    | 2230  |
| Track density, KTPI (ktracks/in avg.)                  | 386   |
| Areal density, (Gb/in <sup>2</sup> avg)                | 867   |
| Spindle speed (RPM)                                    | 7200  |
| Internal data transfer rate (Mb/s max)                 | 2695  |
| Max sustained transfer rate, OD read (MB/s)            | 220   |
| I/O data-transfer rate (MB/s max)                      | 600   |
| ATA data-transfer modes supported                      | PIO modes 0–4<br>Multiword DMA modes 0–2<br>Ultra DMA modes 0–6 |
| Cache buffer   | 256MB   |
| Weight: (maximum)                                      | 650g (1.43 lb)  |
| Average latency  | 4.16ms  |
| Power-on to ready (sec) (typ/max)                      | 20/30   |
| Standby to ready (sec) (typ/max)                       | 20/30   |
| Startup current (typical) 12V (peak)                   | <=1.8A  |
| Voltage tolerance (including noise)                    | 5V ±5%<br>12V ±10%  |
| Non-Operating (Ambient °C)                             | –40° to 70°   |
| Operating ambient temperature (min °C)                 | 0°  |
| Operating temperature (drive case max °C)              | 60° †   |
| Temperature gradient (°C per hour max)                 | 20°C (operating)<br>30°C (non-operating)                        |
| Relative humidity                                      | 5% to 95% (operating)<br>5% to 95% (non-operating)              |
| Relative humidity gradient                             | 30% per hour max  |
| Altitude, operating                                    | –304.8 m to 3,048 m<br>(–1000 ft to 10,000+ ft)                 |
| Altitude, non-operating<br>(below mean sea level, max) | –304.8 m to 12,192 m<br>(–1000 ft to 40,000+ ft)                |
| Operational Shock (max at 2 ms)                        | Read 70 Gs / Write 40 Gs  |
| Non-Operational Shock (max at 2 ms)                    | 250 Gs  |

| Drive specification*   | ST1000DM0004   |
|--|--|
| Vibration, operating   | 5–22 Hz: 0.25 Gs, Limited displacement<br>22–350 Hz: 0.50 Gs<br>350–500 Hz: 0.25 Gs  |
| Operation Rotational vibration                                       | 20–1500Hz: 12.5 rads/s <sup>2</sup>  |
| Vibration, non-operating   | 2–500 Hz: 2.27 Grms ref  |
| Drive acoustics, sound power (bels)                                  |  |
| Idle***  | 2.8 (typical)<br>3.0 (max)   |
| Performance seek   | 3.2 (typical)<br>3.4 (max)   |
| Non-recoverable read errors  | 1 sector per 10 <sup>15</sup> bits read  |
| Annualized Failure Rate (AFR)  | <1% based on 8760 POH  |
| Rated Workload   | Average annualized workload rating: <300TB/year<br>The AFR specification for the product assumes the I/O workload does not exceed the average annualized workload rate limit of 300 TB/year. Workloads exceeding the annualized rate may degrade the product AFR and impact reliability as experienced by the particular application. The average annualized workload rate limit is in units of TB per calendar year.  |
| Warranty   | To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/warranty-and-replacements/">http://www.seagate.com/support/warranty-and-replacements/</a> . From this page, click on the "Is my Drive under Warranty" link. The following are required to be provided: the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for the drive. |
| Load-unload cycles   | 300,000  |
| Supports Hotplug operation per Serial ATA Revision 3.2 specification | Yes  |

\* All specifications above are based on native configurations.

\*\* One GB equals one billion bytes and 1TB equals one trillion bytes when referring to hard drive capacity.

Accessible capacity may vary depending on operating environment and formatting.

\*\*\* During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

† Seagate does not recommend operating at sustained case temperatures above 60°C.

Operating at higher temperatures will reduce useful life of the product.



## 2.2 Formatted capacity

| ST models     | Formatted capacity* | Guaranteed sectors | Bytes per logical sector |
|---------------|---------------------|--------------------|--------------------------|
| ST10000DM0004 | 10TB                | 7,814,037,168      | 512                      |

\*One GB equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting..

|             |   |
|-------------|---|
| <b>Note</b> | LBA Counts for drive capacities greater than 8TB are calculated based upon the SFF-8447 standard publication. <a href="ftp://ftp.seagate.com/sff/SFF-8447.PDF">ftp://ftp.seagate.com/sff/SFF-8447.PDF</a> |
|-------------|---|

### 2.2.1 LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to  $n-1$ , where  $n$  is the number of guaranteed sectors as defined above.

See Section 4.3.1, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137GB.

## 2.3 Recording and interface technology

|  |                        |
|--|------------------------|
| Interface                              | Serial ATA (SATA)      |
| Recording method                       | Perpendicular          |
| Recording density, KBPI (Kb/in max)    | 2230                   |
| Track density, KTPI (ktracks/in avg)   | 386                    |
| Areal density (Gb/in <sup>2</sup> avg) | 867                    |
| Spindle speed (RPM) ( $\pm 0.2\%$ )    | 7200                   |
| Internal data transfer rate (Mb/s max) | 2695                   |
| Maximum Sustained transfer rate (MB/s) | 220                    |
| I/O data-transfer rate (MB/s max)      | 600 (Ultra DMA mode 5) |

## 2.4 Start/stop times

|                                   |       |
|-----------------------------------|-------|
| Power-on to Ready (sec) (typ/max) | 20/30 |
| Standby to Ready (sec) (typ/max)  | 20/30 |
| Ready to spindle stop (sec) (max) | 20    |

## 2.5 Power specifications

The drive receives DC power (+5V or +12V) through a native SATA power connector. See Figure 3 on page 20.

### 2.5.1 Power consumption

Power requirements for the drives are listed in Table 2. Typical power measurements are based on an average of drives tested, under nominal conditions, using 5.0V and 12.0V input voltage at 25°C ambient temperature.

**Table 2 DC power requirements (10TB)**

|  |                   | 6.0Gb mode |      |       |
|--|-------------------|------------|------|-------|
| Voltage  |                   | +5V        | +12V | Watts |
| Regulation   |                   | ± 5%       |      | Total |
| <b>Avg Idle Current *</b>                          |                   | 0.26       | 0.26 | 4.42  |
| <b>Advanced Idle Current *</b>                     |                   |            |      |       |
|  | Idle_A            | 0.25       | 0.26 | 4.36  |
|  | Idle_B            | 0.16       | 0.18 | 2.98  |
|  | Idle_C            | 0.17       | 0.12 | 2.34  |
|  | Standby           | 0.15       | 0.00 | 0.80  |
| <b>Maximum Start Current</b>                       |                   |            |      |       |
|  | DC (peak DC)      | 0.58       | 1.94 |       |
|  | AC (Peak DC)      | 0.79       | 2.70 |       |
| Delayed Motor Start (DC max)                       |                   | 0.26       | 0.75 |       |
| <b>Operating current (random read 4K16Q):</b>      |                   |            |      |       |
|  | Typical DC        | 0.31       | 0.57 | 8.37  |
|  | Maximum DC        | 0.32       | 0.59 |       |
|  | Maximum DC (peak) | 0.96       | 2.24 |       |
| <b>Operating current (random write 4K16Q)</b>      |                   |            |      |       |
|  | Typical DC        | 0.32       | 0.56 | 8.31  |
|  | Maximum DC        | 0.33       | 0.57 |       |
|  | Maximum DC (peak) | 0.70       | 2.26 |       |
| <b>Operating current (sequential read 64K16Q)</b>  |                   |            |      |       |
|  | Typical DC        | 0.65       | 0.28 | 6.59  |
|  | Maximum DC        | 0.67       | 0.28 |       |
|  | Maximum DC (peak) | 1.11       | 0.71 |       |
| <b>Operating current (sequential write 64K16Q)</b> |                   |            |      |       |
|  | Typical DC        | 0.58       | 0.31 | 6.57  |
|  | Maximum DC        | 0.60       | 0.31 |       |
|  | Maximum DC (peak) | 0.78       | 0.71 |       |

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels

### 2.5.1.1 Typical current profiles



Figure 1. 10TB Typical 5V and 12V startup and operation current profiles

### 2.5.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 80-ohm resistive load on the +12 V line or an equivalent 15-ohm resistive load on the +5V line.

- Using 12V power, the drive is expected to operate with a maximum of 120mV peak-to-peak square-wave injected noise at up to 10MHz.
- Using 5V power, the drive is expected to operate with a maximum of 100mV peak-to-peak square-wave injected noise at up to 10MHz.

**Note** Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

### 2.5.3 Voltage tolerance

Voltage tolerance (including noise):

5V ±5%                      12V ± 10%

## 2.5.4 Extended Power Conditions - PowerChoice™

Utilizing the load/unload architecture a programmable power management interface is provided to tailor systems for reduced power consumption and performance requirements.

The table below lists the supported power conditions available in PowerChoice. Power conditions are ordered from highest power consumption (and shortest recovery time) to lowest power consumption (and longest recovery time) as follows: Idle\_a power >= Idle\_b power >= Idle\_c power >= Standby\_z power. The further users go down in the table, the more power savings is actualized. For example, Idle\_b results in greater power savings than the Idle\_a power condition. Standby results in the greatest power savings.

| Power Condition Name | Power Condition ID | Description  |
|----------------------|--------------------|--|
| Idle_a               | 81 <sub>H</sub>    | Reduced electronics                                |
| Idle_b               | 82 <sub>H</sub>    | Heads unloaded. Disks spinning at full RPM         |
| Idle_c               | 83 <sub>H</sub>    | Heads unloaded. Disks spinning at reduced RPM      |
| Standby_z            | 00 <sub>H</sub>    | Heads unloaded. Motor stopped (disks not spinning) |

Each power condition has a set of current, saved and default settings. Default settings are not modifiable. Default and saved settings persist across power-on resets. The current settings do not persist across power-on resets. At the time of manufacture, the default, saved and current settings are in the Power Conditions log match.

### PowerChoice is invoked using one of two methods

- Automatic power transitions which are triggered by expiration of individual power condition timers. These timer values may be customized and enabled using the Extended Power Conditions (EPC) feature set using the standardized Set Features command interface.
- Immediate host commanded power transitions may be initiated using an EPC Set Features "Go to Power Condition" subcommand to enter any supported power condition. Legacy power commands Standby Immediate and Idle Immediate also provide a method to directly transition the drive into supported power conditions.

### PowerChoice exits power saving states under the following conditions

- Any command which requires the drive to enter the PM0: Active state (media access)
- Power on reset

### PowerChoice provides the following reporting methods for tracking purposes

Check Power Mode Command

- Reports the current power state of the drive

Identify Device Command

- EPC Feature set supported flag
- EPC Feature enabled flag is set if at least one Idle power condition timer is enabled

Power Condition Log reports the following for each power condition

- Nominal recovery time from the power condition to active
- If the power condition is Supported, Changeable, and Savable
- Default enabled state, and timer value
- Saved enabled state, and timer value
- Current enabled state, and timer value

S.M.A.R.T. Read Data Reports

- Attribute 192 - Emergency Retract Count
- Attribute 193 - Load/Unload Cycle Count

### PowerChoice Manufacture Default Power Condition Timer Values

Default power condition timer values have been established to assure product reliability and data integrity. A minimum timer value threshold of two minutes ensures the appropriate amount of background drive maintenance activities occur. Attempting to set a timer values less than the specified minimum timer value threshold will result in an aborted EPC "Set Power Condition Timer" subcommand.

| Power Condition Name | Manufacturer Default Timer Values |
|----------------------|-----------------------------------|
| Idle_a               | 100ms                             |
| Idle_b               | 2 min                             |
| Idle_c               | 4 min                             |
| Standby_z            | 15 min                            |

Setting power condition timer values less than the manufacturer specified defaults or issuing the EPC "Go to Power Condition" subcommand at a rate exceeding the default timers may limit this products reliability and data integrity.

### PowerChoice Supported Extended Power Condition Feature Subcommands

| EPC Subcommand  | Description                      |
|-----------------|----------------------------------|
| 00 <sub>H</sub> | Restore Power Condition Settings |
| 01 <sub>H</sub> | Go to Power Condition            |
| 02 <sub>H</sub> | Set Power Condition Timer        |
| 03 <sub>H</sub> | Set Power Condition State        |
| 04 <sub>H</sub> | Enable EPC Feature Set           |
| 05 <sub>H</sub> | Disable EPC Feature Set          |

### PowerChoice Supported Extended Power Condition Identifiers

| Power Condition Identifiers | Power Condition Name     |
|-----------------------------|--------------------------|
| 00 <sub>H</sub>             | Standby_z                |
| 01 - 80 <sub>H</sub>        | Reserved                 |
| 81 <sub>H</sub>             | Idle_a                   |
| 82 <sub>H</sub>             | Idle_b                   |
| 83 <sub>H</sub>             | Idle_c                   |
| 84 - FE <sub>H</sub>        | Reserved                 |
| FF <sub>H</sub>             | All EPC Power Conditions |

## 2.6 Environmental limits

Temperature and humidity values experienced by the drive must be such that condensation does not occur on any drive part. Altitude and atmospheric pressure specifications are referenced to a standard day at 58.7°F (14.8°C).

**Note** To maintain optimal performance drives should be run at nominal drive temperatures and humidity.

### 2.6.1 Temperature

#### a. Operating

32°F to 140°F (0°C to 60°C) drive case temperature range with a maximum temperature gradient of 36°F (20°C) per hour.

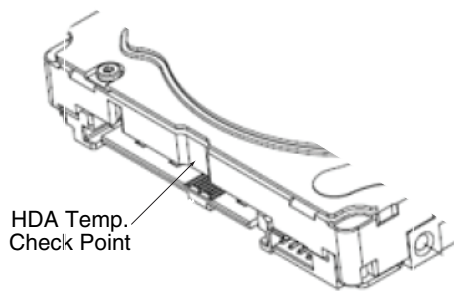
The maximum allowable drive case temperature is 140°F (60°C).

**Note** Seagate does not recommend operating at sustained case temperatures above 60°C. Operating at higher temperatures will reduce useful life of the product.

Air flow may be required to achieve consistent nominal case temperature values (see Section 3.4). To confirm that the required cooling is provided for the electronics and HDA, place the drive in its final mechanical configuration, and perform random write/read operations. After the temperatures stabilize, measure the case temperature of the drive. See Figure 2 for HDA temperature checkpoint.

#### b. Non-operating

–40° to 158°F (–40° to 70°C) package ambient with a maximum gradient of 36°F (20°C) per hour. This specification assumes that the drive is packaged in the shipping container designed by Seagate for use with drive.



**Figure 2.** Location of the HDA temperature check point

**Note** Image is for reference only, may not represent actual drive

### 2.6.2 Humidity

The values below assume that no condensation on the drive occurs. Maximum wet bulb temperature is 84.2°F (29°C).

#### 2.6.2.1 Relative humidity

|               |   |
|---------------|---|
| Operating:    | 5% to 95% non-condensing relative humidity with a maximum gradient of 20% per hour. |
| Nonoperating: | 5% to 95% non-condensing relative humidity with a maximum gradient of 20% per hour. |

#### 2.6.3 Effective Altitude (sea level)

|               |   |
|---------------|---|
| Operating:    | –304.8 m to 3048 m (–1000 ft. to 10,000+ ft.)   |
| Nonoperating: | –304.8 m to 12,192 m (–1000 ft. to 40,000+ ft.) |

## 2.6.4 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

### 2.6.4.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 70 Gs (read) and 40 Gs (write) based on half-sine shock pulses of 2ms. Shocks should not be repeated more than two times per second.

### 2.6.4.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 250 Gs based on a nonrepetitive half-sine shock pulse of 2ms duration.

## 2.6.5 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

### 2.6.5.1 Operating vibration

The maximum vibration levels that the drive may experience while meeting the performance standards specified in this document are specified below.

|                        |                                 |
|------------------------|---------------------------------|
| 5–22 Hz                | 0.25 Gs                         |
| 22–350 Hz              | 0.50 Gs                         |
| 350–500 Hz             | 0.25 Gs                         |
| 20 - 1500Hz<br>*(RROV) | 12.5 rads/s <sup>2</sup> w/RVFF |

\* Rotary Random Operating Vibration

### 2.6.5.2 Nonoperating vibration

The maximum nonoperating vibration levels that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation are specified below.

|                           |               |
|---------------------------|---------------|
| 2–500 Hz<br>Linear Random | 2.27 Grms ref |
|---------------------------|---------------|

| Freq (Hz)          | 2    | 4   | 100 | 500  |
|--------------------|------|-----|-----|------|
| G <sup>2</sup> /Hz | .001 | .03 | .03 | .001 |

## 2.7 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels (no pure tones). All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.

|             |   |
|-------------|---|
| <b>Note</b> | For seek mode tests, the drive is placed in seek mode only.<br>The number of seeks per second is defined by the following equation:<br>Number of seeks per second = $0.4 / (\text{average latency} + \text{average access time})$ |
|-------------|---|

**Table 3 Fluid Dynamic Bearing (FDB) motor acoustics**

| Idle*                            | Performance seek                 |
|----------------------------------|----------------------------------|
| 2.8 bels (typ)<br>3.0 bels (max) | 3.2 bels (typ)<br>3.4 bels (max) |

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.8 Test for Prominent Discrete Tones (PDTs)

Seagate follows the ECMA-74 standards for measurement and identification of PDTs. An exception to this process is the use of the absolute threshold of hearing. Seagate uses this threshold curve (originated in ISO 389-7) to discern tone audibility and to compensate for the inaudible components of sound prior to computation of tone ratios according to Annex D of the ECMA-74 standards.

## 2.9 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

**Table 4 Radio frequency environments**

| Test                      | Description   | Performance level | Reference standard                |
|---------------------------|---|-------------------|-----------------------------------|
| Electrostatic discharge   | Contact, HCP, VCP: $\pm 4$ kV; Air: $\pm 8$ kV  | B                 | EN 61000-4-2: 95                  |
| Radiated RF immunity      | 80 to 1000 MHz, 3 V/m,<br>80% AM with 1 kHz sine<br>900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz | A                 | EN 61000-4-3: 96<br>ENV 50204: 95 |
| Electrical fast transient | $\pm 1$ kV on AC mains, $\pm 0.5$ kV on external I/O  | B                 | EN 61000-4-4: 95                  |
| Surge immunity            | $\pm 1$ kV differential, $\pm 2$ kV common, AC mains  | B                 | EN 61000-4-5: 95                  |
| Conducted RF immunity     | 150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine   | A                 | EN 61000-4-6: 97                  |
| Voltage dips, interrupts  | 0% open, 5 seconds<br>0% short, 5 seconds<br>40%, 0.10 seconds<br>70%, 0.01 seconds               | C<br>C<br>C<br>B  | EN 61000-4-11: 94                 |



## 2.10 Reliability

### 2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF)

The production disk drive shall achieve an annualized failure-rate of <1% (MTBF of 1,000,000 hours) over a 5 year service life when used in Storage field conditions as limited by the following:

- 8760 power-on hours per year.
- HDA temperature as reported by the drive  $\leq 30^{\circ}\text{C}$
- Ambient wet bulb temp  $\leq 26^{\circ}\text{C}$
- Typical workload
- The AFR (MTBF) is a population statistic not relevant to individual units
- ANSI/ISA S71.04-2013 G2 classification levels and dust contamination to ISO 14644-1 Class 8 standards (as measured at the device)

The MTBF specification for the drive assumes the operating environment is designed to maintain nominal drive temperature and humidity. Occasional excursions in operating conditions between the rated MTBF conditions and the maximum drive operating conditions may occur without significant impact to the rated MTBF. However continual or sustained operation beyond the rated MTBF conditions will degrade the drive MTBF and reduce product reliability..

|                            |  |
|----------------------------|--|
| Nonrecoverable read errors | 1 per $10^{15}$ bits read, max   |
| Load unload cycles         | 300,000 cycles   |
| Rated Workload             | Average annualized workload rating: <300TB/year<br>The AFR specification for the product assumes the I/O workload does not exceed the average annualized workload rate limit of 300 TB/year. Workloads exceeding the annualized rate may degrade the product AFR and impact reliability as experienced by the particular application. The average annualized workload rate limit is in units of TB per calendar year.  |
| Warranty                   | To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/warranty-and-replacements/">http://www.seagate.com/support/warranty-and-replacements/</a> . From this page, click on the "Is my Drive under Warranty" link. The following are required to be provided: the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for the drive. |
| Preventive maintenance     | None required.   |

### 2.10.2 Storage

Maximum storage periods are 180 days within original unopened Seagate shipping package or 60 days unpackaged within the defined non-operating limits (refer to environmental section in this manual). Storage can be extended to 1 year packaged or unpackaged under optimal environmental conditions ( $25^{\circ}\text{C}$ , <40% relative humidity non-condensing, and non-corrosive environment). During any storage period the drive non-operational temperature, humidity, wet bulb, atmospheric conditions, shock, vibration, magnetic and electrical field specifications should be followed.

### 2.10.3 Warranty

To determine the warranty for a specific drive, use a web browser to access the following web page:

<http://www.seagate.com/support/warranty-and-replacements/>

From this page, click on "Is my Drive under Warranty". Users will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for the drive.

## 2.11 Agency certification

### 2.11.1 Safety certification

These products are certified to meet the requirements of UL60950-1, CSA60950-1 and EN60950 and so marked as to the certify agency.

### 2.11.2 Electromagnetic compatibility

Hard drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (2004/108/EC) as put into place 20 July 2007. Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

#### **Korean RRA**

If these drives have the Korean Communications Commission (KCC) logo, they comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Agency (RRA) Communications Commission, Republic of Korea.

These drives have been tested and comply with the Electromagnetic Interference/Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

#### **Canada ICES-003**

If this model has the ICES-003 Marking it complies with the Canadian Standard Association Standard CAN/CSA-CISPR 22-10, Information Technology Equipment - Radio Disturbance Characteristics - Limits and Methods of Measurement.

#### **Australian RCM Mark**

If these models have the RCM marking, they comply with the Australia/New Zealand Standard AS/NZ CISPR22 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication and Media Authority (ACMA).

### 2.11.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disk drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

**Radio and television interference.** This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, users are encouraged to try one or more of the following corrective measures:

- Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, users should consult the dealer or an experienced radio/television technician for additional suggestions. Users may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

## 2.12 Environmental protection

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

### 2.12.1 European Union Restriction of Hazardous Substances (RoHS) Directive

The European Union Restriction of Hazardous Substances (RoHS) Directive, restricts the presence of chemical substances, including Lead, Cadmium, Mercury, Hexavalent Chromium, PBB and PBDE, in electronic products, effective July 2006. This drive is manufactured with components and materials that comply with the RoHS Directive.

### 2.12.2 China Requirements — China RoHS 2

China RoHS 2 refers to the Ministry of Industry and Information Technology Order No. 32, effective July 1, 2016, titled Management Methods for the Restriction of the Use of Hazardous Substances in Electrical and Electronic Products. To comply with China RoHS 2, we determined this product's Environmental Protection Use Period (EPUP) to be 20 years in accordance with the *Marking for the Restricted Use of Hazardous Substances in Electronic and Electrical Products*, SJ/T 11364-2014.

## 中国电器电子产品有害物质限制使用管理办法

(Management Methods for the Restriction of the Use of Hazardous Substances in Electrical and Electronic Products \_ China RoHS)



## 产品中有害物质的名称及含量

(Name and Content of the Hazardous Substances in Product)

**Table 5 Hazardous Substances**

| 部件名称<br>Part Name | 有害物质<br>Hazardous Substances |                      |                      |  |   |  |
|-------------------|------------------------------|----------------------|----------------------|--|---|--|
|                   | 铅<br>Lead<br>(Pb)            | 汞<br>Mercury<br>(Hg) | 镉<br>Cadmium<br>(Cd) | 六价铬<br>Hexavalent<br>Chromium<br>(CF (VI)) | 多溴联苯<br>Polybrominated<br>biphenyls (PBB) | 多溴二苯醚<br>Polybrominated<br>diphenyl ethers<br>(PBDE) |
| 印刷电路板组装<br>PCBA   | X                            | O                    | O                    | O  | O   | O  |
| 机壳<br>Chassis     | X                            | O                    | O                    | O  | O   | O  |

本表格依据 SJ/T 11364 的规定编制。

This table is prepared in accordance with the provisions of SJ/T 11364-2014

**O:** 表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。

**O:** Indicates that the hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement of GB/T26572.

**X:** 表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。

**X:** Indicates that the hazardous substance contained in at least one of the homogeneous materials used for this part is above the limit requirement of GB/T26572.

## **2.13 Corrosive environment**

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment.

Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in hard disk drives are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

Seagate recommends that data centers be kept clean by monitoring and controlling the dust and gaseous contamination. Gaseous contamination should be within ANSI/ISA S71.04-2013 G2 classification levels (as measured on copper and silver coupons), and dust contamination to ISO 14644-1 Class 8 standards, and MTBF rated conditions as defined in the Annualized Failure Rate (AFR) and Mean Time Between Failure (MTBF) section.

## **2.14 Shipping, Repair and Returns**

### **Shipping**

When transporting or shipping a drive, use only a Seagate-approved container. Keep the original box. Seagate approved containers are easily identified by the Seagate Approved Package label. Shipping a drive in a non-approved container voids the drive warranty.

Seagate repair centers may refuse receipt of components improperly packaged or obviously damaged in transit. Contact the authorized Seagate distributor to purchase additional boxes. Seagate recommends shipping by an air-ride carrier experienced in handling computer equipment.

### **Product repair and return information**

Seagate customer service centers are the only facilities authorized to service Seagate drives. Seagate does not sanction any third-party repair facilities. Any unauthorized repair or tampering with the factory seal voids the warranty.

## 3.0 Configuring and mounting the drive

This section contains the specifications and instructions for configuring and mounting the drive.

### 3.1 Handling and static-discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

|                |  |
|----------------|--|
| <b>Caution</b> | <ul style="list-style-type: none"><li>• Before handling the drive, put on a grounded wrist strap, or ground oneself frequently by touching the metal chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire installation procedure.</li><li>• Handle the drive by its edges or frame <i>only</i>.</li><li>• The drive is extremely fragile—handle it with care. Do not press down on the drive top cover.</li><li>• Always rest the drive on a padded, antistatic surface until mounting it in the computer.</li><li>• Do not touch the connector pins or the printed circuit board.</li><li>• Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.</li></ul> |
|----------------|--|

### 3.2 Configuring the drive

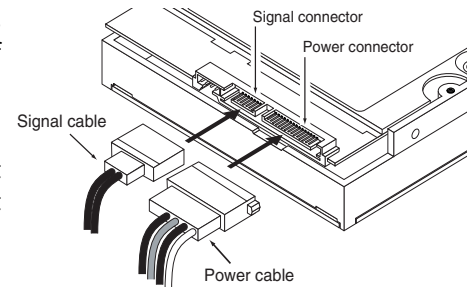
Each drive on the Serial ATA interface connects point-to-point with the Serial ATA host adapter. There is no master/slave relationship because each drive is considered a master in a point-to-point relationship. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both “masters” on two separate ports. Both drives behave as if they are Device 0 (master) devices.

### 3.3 Serial ATA cables and connectors

The Serial ATA interface cable consists of four conductors in two differential pairs, plus three ground connections. The cable size may be 30 to 26 AWG with a maximum length of one meter (39.37 in). See Table 6 for connector pin definitions. Either end of the SATA signal cable can be attached to the drive or host.

For direct backplane connection, the drive connectors are inserted directly into the host receptacle. The drive and the host receptacle incorporate features that enable the direct connection to be hot pluggable and blind mateable.

For installations which require cables, users can connect the drive as illustrated in Figure 3.



**Figure 3. Attaching SATA cabling**

Each cable is keyed to ensure correct orientation. BarraCuda Pro Serial ATA drives support latching SATA connectors.

### 3.4 Drive mounting

Users can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See Figure 4 for drive mounting dimensions. Follow these important mounting precautions when mounting the drive:

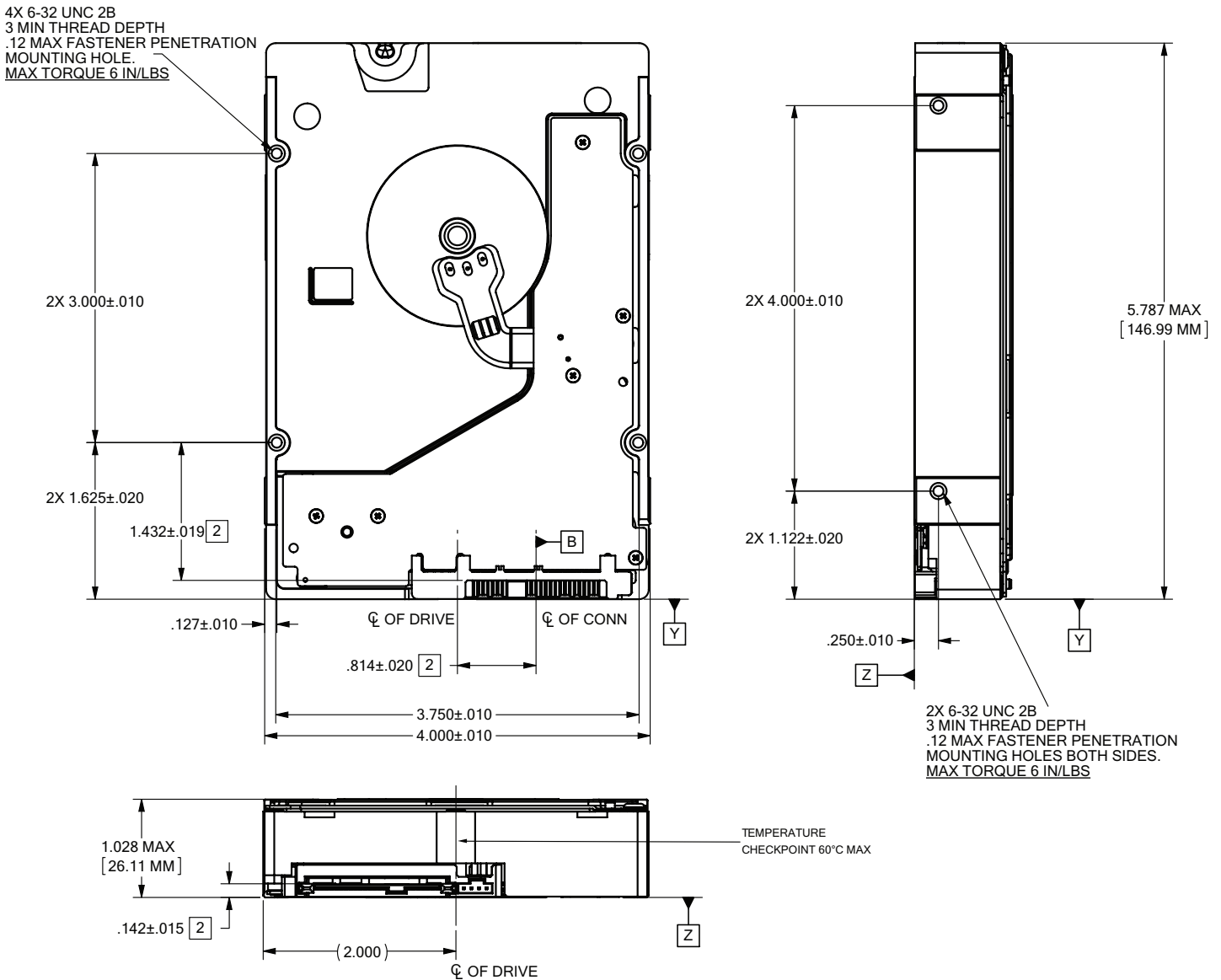
- Allow a minimum clearance of 0.030 in (0.76mm) around the entire perimeter of the drive for cooling.
- Use only 6-32 UNC mounting screws.
- The screws should be inserted no more than 0.120 in (3.05mm) into the bottom or side mounting holes.
- Do not overtighten the mounting screws (maximum torque: 6 in-lb).

#### 3.4.1 Mechanical specifications

Refer to Figure 4 for detailed mounting configuration dimensions. See Section 3.4, "Drive mounting."

|                |             |         |       |
|----------------|-------------|---------|-------|
| <b>Weight:</b> | 10TB models | 1.43 lb | 650 g |
|----------------|-------------|---------|-------|

**Note** These dimensions conform to the Small Form Factor Standard documented in SFF-8301 and SFF-8323, found at [www.sffcommittee.org](http://www.sffcommittee.org)



**Figure 4. Mounting configuration dimensions (10TB models)**

**Note** The image is for mechanical dimension reference only and may not represent the actual drive.

## 4.0 Serial ATA (SATA) interface

These drives use the industry-standard Serial ATA interface that supports FIS data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–6.

For detailed information about the Serial ATA interface, refer to the “Serial ATA: High Speed Serialized AT Attachment” specification.

### 4.1 Hot-Plug compatibility

BarraCuda Pro Serial ATA drives incorporate connectors which enable users to hot plug these drives in accordance with the Serial ATA Revision 3.2 specification. This specification can be downloaded from [www.serialata.org](http://www.serialata.org).

#### Caution:

The drive motor must come to a complete stop (**Ready to spindle stop time indicated in Section 2.4**) prior to changing the plane of operation. This time is required to insure data integrity.

### 4.2 Serial ATA device plug connector pin definitions

Table 6 summarizes the signals on the Serial ATA interface and power connectors.

**Table 6 Serial ATA connector pin definitions**

| Segment   | Pin | Function             | Definition                                    |
|---|-----|----------------------|---|
| <b>Signal</b>   | S1  | Ground               | 2nd mate                                      |
|   | S2  | A+                   | Differential signal pair A from Phy           |
|   | S3  | A-                   |   |
|   | S4  | Ground               | 2nd mate                                      |
|   | S5  | B-                   | Differential signal pair B from Phy           |
|   | S6  | B+                   |   |
|   | S7  | Ground               | 2nd mate                                      |
| <b>Key and spacing separate signal and power segments</b> |     |                      |   |
| <b>Power</b>  | P1  | V <sub>33</sub>      | 3.3V power                                    |
|   | P2  | V <sub>33</sub>      | 3.3V power                                    |
|   | P3  | V <sub>33</sub>      | 3.3V power, pre-charge, 2nd mate              |
|   | P4  | Ground               | 1st mate                                      |
|   | P5  | Ground               | 2nd mate                                      |
|   | P6  | Ground               | 2nd mate                                      |
|   | P7  | V <sub>5</sub>       | 5V power, pre-charge, 2nd mate                |
|   | P8  | V <sub>5</sub>       | 5V power                                      |
|   | P9  | V <sub>5</sub>       | 5V power                                      |
|   | P10 | Ground               | 2nd mate                                      |
|   | P11 | Ground or LED signal | If grounded, drive does not use deferred spin |
|   | P12 | Ground               | 1st mate.                                     |
|   | P13 | V <sub>12</sub>      | 12V power, pre-charge, 2nd mate               |
|   | P14 | V <sub>12</sub>      | 12V power                                     |
|   | P15 | V <sub>12</sub>      | 12V power                                     |

#### Notes:

- All pins are in a single row, with a 1.27mm (0.050") pitch.
- The comments on the mating sequence apply to the case of backplane blindmate connector only. In this case, the mating sequences are:
  - the ground pins P4 and P12.
  - the pre-charge power pins and the other ground pins.
  - the signal pins and the rest of the power pins.
- There are three power pins for each voltage. One pin from each voltage is used for pre-charge when installed in a blind-mate backplane configuration.
- All used voltage pins (V<sub>x</sub>) must be terminated.

### 4.3 Supported ATA commands

The following table lists Serial ATA standard commands that the drive supports. For a detailed description of the ATA commands, refer to the Serial ATA: High Speed Serialized AT Attachment specification. See “S.M.A.R.T. commands” on page 29 for details and subcommands used in the S.M.A.R.T. implementation.

**Table 7 Supported ATA commands**

| Command name                         | Command code (in hex)               |
|--------------------------------------|-------------------------------------|
| Accessible Max Address Configuration |                                     |
| Get Native Max Address Ext           | 78 <sub>H</sub> / 0000 <sub>H</sub> |
| Set Accessible Max Address Ext       | 78 <sub>H</sub> / 0001 <sub>H</sub> |
| Freeze Accessible Max Address Ext    | 78 <sub>H</sub> / 0002 <sub>H</sub> |
| Check Power Mode                     | E5 <sub>H</sub>                     |
| Download Microcode                   | 92 <sub>H</sub>                     |
| Execute Device Diagnostics           | 90 <sub>H</sub>                     |
| Flush Cache                          | E7 <sub>H</sub>                     |
| Flush Cache Extended                 | EA <sub>H</sub>                     |
| Identify Device                      | EC <sub>H</sub>                     |
| Idle                                 | E3 <sub>H</sub>                     |
| Idle Immediate                       | E1 <sub>H</sub>                     |
| NoP                                  | 00 <sub>H</sub>                     |
| Read Buffer                          | E4 <sub>H</sub>                     |
| Read Buffer DMA                      | E9 <sub>H</sub>                     |
| Read DMA                             | C8 <sub>H</sub>                     |
| Read DMA Extended                    | 25 <sub>H</sub>                     |
| Read FPDMA Queued                    | 60 <sub>H</sub>                     |
| Read Log DMA Ext                     | 47 <sub>H</sub>                     |
| Read Log Ext                         | 2F <sub>H</sub>                     |
| Read Multiple                        | C4 <sub>H</sub>                     |
| Read Multiple Extended               | 29 <sub>H</sub>                     |
| Read Sectors                         | 20 <sub>H</sub>                     |
| Read Sectors Extended                | 24 <sub>H</sub>                     |
| Read Sectors Without Retries         | 21 <sub>H</sub>                     |
| Read Verify Sectors                  | 40 <sub>H</sub>                     |
| Read Verify Sectors Extended         | 42 <sub>H</sub>                     |
| Read Verify Sectors Without Retries  | 41 <sub>H</sub>                     |
| Receive FPDMA Queued                 | 65 <sub>H</sub>                     |
| Request Sense Data Ext               | 0B <sub>H</sub>                     |
| Sanitize Device - Overwrite Ext      | B4 <sub>H</sub> / 0014 <sub>H</sub> |
| Sanitize Device - Freeze Lock Ext    | B4 <sub>H</sub> / 0020 <sub>H</sub> |
| Sanitize Device - Status Ext         | B4 <sub>H</sub> / 0000 <sub>H</sub> |
| Security Disable Password            | F6 <sub>H</sub>                     |
| Security Erase Prepare               | F3 <sub>H</sub>                     |
| Security Erase Unit                  | F4 <sub>H</sub>                     |
| Security Freeze                      | F5 <sub>H</sub>                     |
| Security Set Password                | F1 <sub>H</sub>                     |



| <b>Command name</b>                  | <b>Command code (in hex)</b>      |
|--------------------------------------|-----------------------------------|
| Security Unlock                      | F2 <sub>H</sub>                   |
| Seek                                 | 70 <sub>H</sub>                   |
| Send FPDMA Queued                    | 64 <sub>H</sub>                   |
| Set Date & Time Ext                  | 77 <sub>H</sub>                   |
| Set Features                         | EF <sub>H</sub>                   |
| Set Multiple Mode                    | C6 <sub>H</sub>                   |
| Sleep                                | E6 <sub>H</sub>                   |
| S.M.A.R.T. Disable Operations        | B0 <sub>H</sub> / D9 <sub>H</sub> |
| S.M.A.R.T. Enable/Disable Autosave   | B0 <sub>H</sub> / D2 <sub>H</sub> |
| S.M.A.R.T. Enable Operations         | B0 <sub>H</sub> / D8 <sub>H</sub> |
| S.M.A.R.T. Execute Offline           | B0 <sub>H</sub> / D4 <sub>H</sub> |
| S.M.A.R.T. Read Attribute Thresholds | B0 <sub>H</sub> / D1 <sub>H</sub> |
| S.M.A.R.T. Read Data                 | B0 <sub>H</sub> / D0 <sub>H</sub> |
| S.M.A.R.T. Read Log Sector           | B0 <sub>H</sub> / D5 <sub>H</sub> |
| S.M.A.R.T. Return Status             | B0 <sub>H</sub> / DA <sub>H</sub> |
| S.M.A.R.T. Save Attribute Values     | B0 <sub>H</sub> / D3 <sub>H</sub> |
| S.M.A.R.T. Write Log Sector          | B0 <sub>H</sub> / D6 <sub>H</sub> |
| Standby                              | E2 <sub>H</sub>                   |
| Standby Immediate                    | E0 <sub>H</sub>                   |
| Trusted Send                         | 5E <sub>H</sub> (SED drives only) |
| Trusted Send DMA                     | 5F <sub>H</sub> (SED drives only) |
| Trusted Receive                      | 5C <sub>H</sub> (SED drives only) |
| Trusted Receive DMA                  | 5D <sub>H</sub> (SED drives only) |
| Write Buffer                         | E8 <sub>H</sub>                   |
| Write Buffer DMA                     | EB <sub>H</sub>                   |
| Write DMA                            | CA <sub>H</sub>                   |
| Write DMA Extended                   | 35 <sub>H</sub>                   |
| Write DMA FUA Extended               | 3D <sub>H</sub>                   |
| Write FPDMA Queued                   | 61 <sub>H</sub>                   |
| Write Log DMA Ext                    | 57 <sub>H</sub>                   |
| Write Log Extended                   | 3F <sub>H</sub>                   |
| Write Multiple                       | C5 <sub>H</sub>                   |
| Write Multiple Extended              | 39 <sub>H</sub>                   |
| Write Multiple FUA Extended          | CE <sub>H</sub>                   |
| Write Sectors                        | 30 <sub>H</sub>                   |
| Write Sectors Without Retries        | 31 <sub>H</sub>                   |
| Write Sectors Extended               | 34 <sub>H</sub>                   |
| Write Uncorrectable                  | 45 <sub>H</sub>                   |

### 4.3.1 Identify Device command

The Identify Device command (command code EC<sub>H</sub>) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 7 on page 23. All reserved bits or words should be set to zero. Parameters listed with an “x” are drive-specific or vary with the state of the drive. See Section 2.0 on page 6 for default parameter settings.

The following commands contain drive-specific features that may not be included in the Serial ATA specification.

| Word  | Description   | Value             |
|-------|---|-------------------|
| 0     | Configuration information:<br>• Bit 15: 0 = ATA; 1 = ATAPI<br>• Bit 7: removable media<br>• Bit 6: removable controller<br>• Bit 0: reserved  | 0C5A <sub>H</sub> |
| 1     | Obsolete  | 16,383            |
| 2     | ATA-reserved  | 0000 <sub>H</sub> |
| 3     | Obsolete  | 16                |
| 4     | Retired   | 0000 <sub>H</sub> |
| 5     | Retired   | 0000 <sub>H</sub> |
| 6     | Obsolete  | 003F <sub>H</sub> |
| 7–9   | Retired   | 0000 <sub>H</sub> |
| 10–19 | Serial number: (20 ASCII characters, 0000 <sub>H</sub> = none)  | ASCII             |
| 20–21 | Retired   | 0000 <sub>H</sub> |
| 22    | Obsolete  | 0000 <sub>H</sub> |
| 23–26 | Firmware revision (8 ASCII character string, padded with blanks to end of string)   | x.xx              |
| 27–46 | Drive model number: (40 ASCII characters, padded with blanks to end of string)  |                   |
| 47    | (Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)   | 8010 <sub>H</sub> |
| 48    | Trusted computing feature set supported bit 0 (SED only)  | 4001 <sub>H</sub> |
| 49    | Standard Standby timer, IORDY supported and may be disabled   | 2F00 <sub>H</sub> |
| 50    | Capabilities  | 4000 <sub>H</sub> |
| 51–52 | Obsolete  | xxxx <sub>H</sub> |
| 53–56 | Words 54–58, 64–70 and 88 are valid   | xxxx <sub>H</sub> |
| 57–58 | Obsolete  | xxxx <sub>H</sub> |
| 59    | (Bit 15: 0) Block Erase Ext Not Supported<br>(Bit 14: 1) Overwrite Ext Supported<br>(Bit 13: X) Crypto Scramble Ext Supported (SED Only)<br>(Bit 12: 1) Sanitize feature set supported<br>(Bit 11: 1) Commands allowed during sanitize op as specified in ACS-3<br>(Bit 10: 1) Sanitize Antifreeze Lock Ext command supported   | SC10 <sub>H</sub> |
| 60–61 | Total number of user-addressable LBA sectors available<br>(see Section for related information)<br><b>*Note:</b> The maximum value allowed in this field is: 0FFFFFFFh (268,435,455 sectors, 137GB). Drives with capacities over 137GB will have 0FFFFFFFh in this field and the actual number of user-addressable LBAs specified in words 100–103. This is required for drives that support the 48-bit addressing feature. | 0FFFFFFFh*        |
| 62    | Obsolete  | 0000 <sub>H</sub> |
| 63    | Multyword DMA active and modes supported (see note following this table)  | xx07 <sub>H</sub> |
| 64    | Advanced PIO modes supported (modes 3 and 4 supported)  | 0003 <sub>H</sub> |
| 65    | Minimum multiword DMA transfer cycle time per word (120 ns)   | 0078 <sub>H</sub> |
| 66    | Recommended multiword DMA transfer cycle time per word (120 ns)   | 0078 <sub>H</sub> |

| Word    | Description  | Value                                |
|---------|--|--------------------------------------|
| 67      | Minimum PIO cycle time without IORDY flow control (240 ns)   | 0078 <sub>H</sub>                    |
| 68      | Minimum PIO cycle time with IORDY flow control (120 ns)  | 0078 <sub>H</sub>                    |
| 69      | Additional supported   | 0008 <sub>H</sub>                    |
| 70–74   | ATA-reserved   | 0000 <sub>H</sub>                    |
| 75      | Queue depth  | 001F <sub>H</sub>                    |
| 76      | Serial ATA capabilities  | 8D0E <sub>H</sub>                    |
| 77      | (Bit 6:1) Send/Receive FPDMA Queued Commands Supported   | xx4x <sub>H</sub>                    |
| 78      | Serial ATA features supported  | xxxx <sub>H</sub>                    |
| 79      | Serial ATA features enabled  | xxxx <sub>H</sub>                    |
| 80      | Major version number   | 07F0 <sub>H</sub>                    |
| 81      | Minor version number   | 0060 <sub>H</sub>                    |
| 82      | Command sets supported   | 306B <sub>H</sub>                    |
| 83      | Command sets supported   | 7561 <sub>H</sub>                    |
| 84      | Command sets support extension (see note following this table)   | 6173 <sub>H</sub>                    |
| 85      | Command sets enabled   | 3069 <sub>H</sub>                    |
| 86      | Command sets enabled   | B441 <sub>H</sub>                    |
| 87      | Command sets enable extension  | 6173 <sub>H</sub>                    |
| 88      | Ultra DMA support and current mode (see note following this table)   | xx7F <sub>H</sub>                    |
| 89      | Security erase time  | xxxx <sub>H</sub>                    |
| 90      | Enhanced security erase time   | xxxx <sub>H</sub>                    |
| 92      | Master password revision code  | FFFE <sub>H</sub>                    |
| 93      | Hardware reset value   | xxxx <sub>H</sub>                    |
| 95–99   | ATA-reserved   | 0000 <sub>H</sub>                    |
| 100–103 | Total number of user-addressable LBA sectors available (see Section for related information). These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFh. | ST10000DM0004 = 7,814,037,168        |
| 104–105 | ATA-reserved   | 0000 <sub>H</sub>                    |
| 106     | Physical/Logical sector size   | 6003 <sub>H</sub>                    |
| 107     | ATA-reserved   | 0000 <sub>H</sub>                    |
| 108–111 | The mandatory value of the world wide name (WWN) for the drive.<br><b>NOTE:</b> This field is valid if word 84, bit 8 is set to 1 indicating 64-bit WWN support.   | Each drive will have a unique value. |
| 112–118 | ATA-reserved   | 0000 <sub>H</sub>                    |
| 119     | Commands and feature sets supported  | 41DE <sub>H</sub>                    |
| 120     | Commands and feature sets supported or enabled   | 409C <sub>H</sub>                    |
| 121–127 | ATA-reserved   | 0000 <sub>H</sub>                    |
| 128     | Security status  | 0021 <sub>H</sub>                    |
| 129–159 | Seagate-reserved   | xxxx <sub>H</sub>                    |
| 160–205 | ATA-reserved   | 0000 <sub>H</sub>                    |
| 206     | SCT Command Transport command set.<br>If bit 0 is set to one, then the device supports SCT Command Transport.<br>Bits 7:2 indicate individual SCT feature support.   | xxBD <sub>H</sub>                    |
| 207–254 | ATA-reserved   | 0000 <sub>H</sub>                    |
| 255     | Integrity word   | xxA5 <sub>H</sub>                    |

|             |   |
|-------------|---|
| <b>Note</b> | See the bit descriptions below for words 63, 84, and 88 of the Identify Drive data. |
|-------------|---|

| <b>Description (if bit is set to 1)</b> |  |
|---|--|
| <b>Bit</b>                              | <b>Word 63</b>   |
| 0                                       | Multiword DMA mode 0 is supported.                                   |
| 1                                       | Multiword DMA mode 1 is supported.                                   |
| 2                                       | Multiword DMA mode 2 is supported.                                   |
| 8                                       | Multiword DMA mode 0 is currently active.                            |
| 9                                       | Multiword DMA mode 1 is currently active.                            |
| 10                                      | Multiword DMA mode 2 is currently active.                            |
| <b>Bit</b>                              | <b>Word 84</b>   |
| 0                                       | SMART error logging is supported.                                    |
| 1                                       | SMART self-test is supported.  |
| 2                                       | Media serial number is supported.                                    |
| 3                                       | Media Card Pass Through Command feature set is supported.            |
| 4                                       | Streaming feature set is supported.                                  |
| 5                                       | GPL feature set is supported.  |
| 6                                       | WRITE DMA FUA EXT and WRITE MULTIPLE FUA EXT commands are supported. |
| 7                                       | WRITE DMA QUEUED FUA EXT command is supported.                       |
| 8                                       | 64-bit World Wide Name is supported.                                 |
| 9-10                                    | Obsolete.  |
| 11-12                                   | Reserved for TLC.  |
| 13                                      | IDLE IMMEDIATE command with IUNLOAD feature is supported.            |
| 14                                      | Shall be set to 1.   |
| 15                                      | Shall be cleared to 0.   |
| <b>Bit</b>                              | <b>Word 88</b>   |
| 0                                       | Ultra DMA mode 0 is supported.                                       |
| 1                                       | Ultra DMA mode 1 is supported.                                       |
| 2                                       | Ultra DMA mode 2 is supported.                                       |
| 3                                       | Ultra DMA mode 3 is supported.                                       |
| 4                                       | Ultra DMA mode 4 is supported.                                       |
| 5                                       | Ultra DMA mode 5 is supported.                                       |
| 6                                       | Ultra DMA mode 6 is supported.                                       |
| 8                                       | Ultra DMA mode 0 is currently active.                                |
| 9                                       | Ultra DMA mode 1 is currently active.                                |
| 10                                      | Ultra DMA mode 2 is currently active.                                |
| 11                                      | Ultra DMA mode 3 is currently active.                                |
| 12                                      | Ultra DMA mode 4 is currently active.                                |
| 13                                      | Ultra DMA mode 5 is currently active.                                |
| 14                                      | Ultra DMA mode 6 is currently active.                                |

### 4.3.2 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows

**Table 8** Set Features command values

|                 |   |
|-----------------|---|
| 02 <sub>H</sub> | Enable write cache ( <i>default</i> ).  |
| 03 <sub>H</sub> | Set transfer mode (based on value in Sector Count register).<br>Sector Count register values: |
| 00 <sub>H</sub> | Set PIO mode to default (PIO mode 2).   |
| 01 <sub>H</sub> | Set PIO mode to default and disable IORDY (PIO mode 2).                                       |
| 08 <sub>H</sub> | PIO mode 0  |
| 09 <sub>H</sub> | PIO mode 1  |
| 0A <sub>H</sub> | PIO mode 2  |
| 0B <sub>H</sub> | PIO mode 3  |
| 0C <sub>H</sub> | PIO mode 4 ( <i>default</i> )   |
| 20 <sub>H</sub> | Multiword DMA mode 0  |
| 21 <sub>H</sub> | Multiword DMA mode 1  |
| 22 <sub>H</sub> | Multiword DMA mode 2  |
| 40 <sub>H</sub> | Ultra DMA mode 0  |
| 41 <sub>H</sub> | Ultra DMA mode 1  |
| 42 <sub>H</sub> | Ultra DMA mode 2  |
| 43 <sub>H</sub> | Ultra DMA mode 3  |
| 44 <sub>H</sub> | Ultra DMA mode 4  |
| 45 <sub>H</sub> | Ultra DMA mode 5  |
| 46 <sub>H</sub> | Ultra DMA mode 6  |
| 10 <sub>H</sub> | Enable use of SATA features   |
| 55 <sub>H</sub> | Disable read look-ahead (read cache) feature.   |
| 82 <sub>H</sub> | Disable write cache   |
| 90 <sub>H</sub> | Disable use of SATA features  |
| AA <sub>H</sub> | Enable read look-ahead (read cache) feature ( <i>default</i> ).                               |
| F1 <sub>H</sub> | Report full capacity available  |

**Note** At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

### 4.3.3 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for disk drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attributes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-5 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4<sub>H</sub>) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <http://www.seagate.com/support/downloads/seatools/>.

This drive is shipped with S.M.A.R.T. features disabled. Users must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

**Table 9 S.M.A.R.T. commands**

| Code in features register | S.M.A.R.T. command                               |
|---------------------------|--|
| D0 <sub>H</sub>           | S.M.A.R.T. Read Data                             |
| D2 <sub>H</sub>           | S.M.A.R.T. Enable/Disable Attribute Autosave     |
| D3 <sub>H</sub>           | S.M.A.R.T. Save Attribute Values                 |
| D4 <sub>H</sub>           | S.M.A.R.T. Execute Off-line Immediate (runs DST) |
| D5 <sub>H</sub>           | S.M.A.R.T. Read Log Sector                       |
| D6 <sub>H</sub>           | S.M.A.R.T. Write Log Sector                      |
| D8 <sub>H</sub>           | S.M.A.R.T. Enable Operations                     |
| D9 <sub>H</sub>           | S.M.A.R.T. Disable Operations                    |
| DA <sub>H</sub>           | S.M.A.R.T. Return Status                         |

|             |   |
|-------------|---|
| <b>Note</b> | If an appropriate code is not written to the Features Register, the command is aborted and 0x04 (abort) is written to the Error register. |
|-------------|---|



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